







## Accelerated Testing of Locking Electrical Connectors

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#### Introduction

- Selection of electrical connectors for a harsh outdoor environment requires extensive testing to validate robustness.
- Each application has it's own special set of requirements which make a standard selection unlikely even for derivative products.
- Stresses such as high vibration, repetitive impact, and dirt intrusion are factors







### **Application**

- The electrical connectors to be selected were for digital communication in an all weather, half ton, hydraulic driven robot with an internal combustion power source
- Sources of stress for the connectors were
  - Engine vibration
  - Foot impact with ground
  - Hydraulic rhythm
  - Frequent Impact with surrounding obstacles







### The Challenge

- Digital communication connections that were exposed to the elements and in a chassis with continuous vibration and impact would likely have a high failure rate if not properly validated and optimized.
- This was confirmed with field testing that saw frequent broken or intermittent communication issues
- The gating factor for the development program was being able to do testing quickly so design iterations could maintain with the program pace.









### **Types of Connectors**

- There were two types of all weather connectors being considered
- Latch-lock
  - Latch-lock have a latching prong that hold the connector in place
- Cam-lock
  - Cam-lock connectors have a twisting collar that passes an over-center feature during rotation (cam) and locks the connector

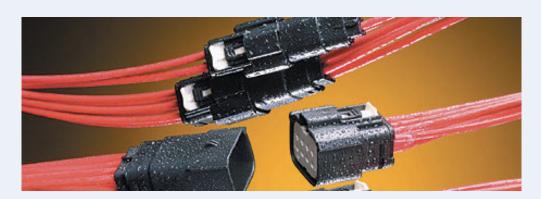


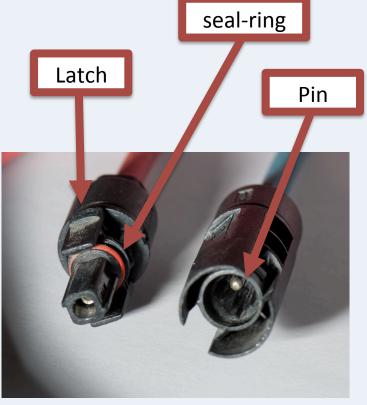




#### **Snap Fit Connector**

Features of a common latch-lock weather proof connector





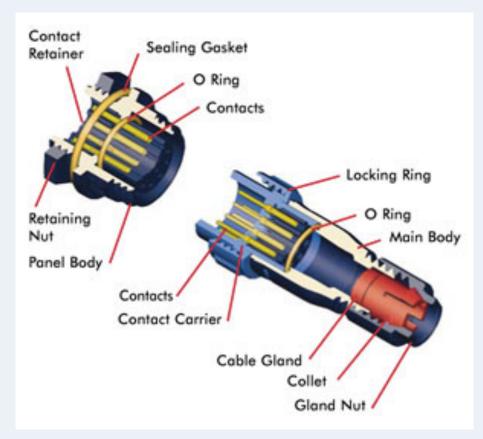






#### Cam Lock Connector

Features of a common cam-lock weather proof connector









### Design Trade Offs

- Both Design could be made weather proof with sealing orings or gaskets
  - The latch lock were light and easy to insert
  - The Cam-lock can handle higher loads but were heavy and create larger harnesses
- The initial selected design was a latch-lock type of connector with a sealing boot
- Instances of intermittent and failed connections were reported in field testing with the robot with this design









## The Testing Need

 A test method that could be done quickly and in a lab environment was needed to assist with selecting a weather proof design robust enough to handle the impact and vibration environment of this application









## **Impact Testing**

- The initial test was based on the premise that a single or short sequence of impacts could be used to correlate connection failure to long term repetitive vibration stress
- Using 50g's as an increment the test was done to the candidate connectors
- It wasn't until 300g's that a failure was observed in the standard latch (weakest) connector
- But the impact tester was taken to it's limit before any other failures could be observed







## 1,500 g Impact

 The impact tester was able to deliver 1,500 g's of force

> This is what 1,500 g's looks like!! Click Image to Play Video



 All other locking connectors were able to withstand this impact, so test could not be used as comparator for all candidate connectors



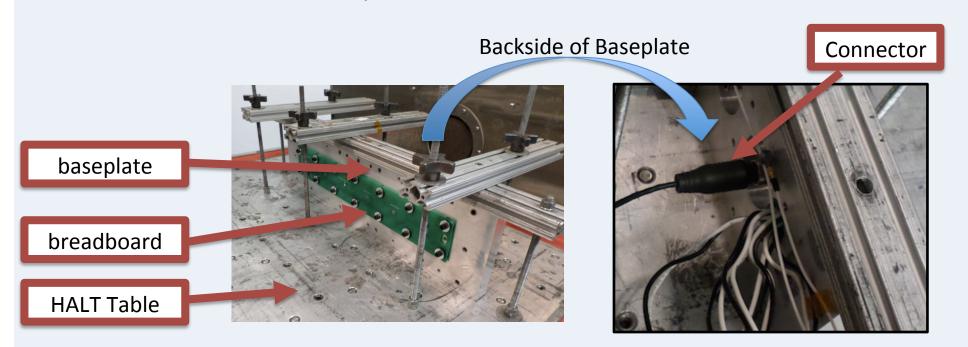






#### Vibration

- Using a HALT chamber, six axis broadband vibration was applied to the "latch-style" and "cam-style" connectors
- Vibration was driven up to 90 Grms with no observed failures











## The Challenge of Failure

- It was becoming apparent that creating enough stress using standard lab techniques to make a strength comparison between locking connectors was difficult
- The effects of long term vibration and repetitive impact in the robot application was difficult to duplicate in a shortened controlled time frame.







#### The Solution

- An additional stress amplifier was needed to create resolution between the robustness of the different connector designs
- This "accelerator" had to be adjustable in orders of magnitude so comparative performance could be discovered and then focused on
- The solution was creating an adjustable cantilevered load on the connectors to be used during HALT vibration or impact testing







#### The Solution

- The variable cantilevered load was created by clamping threaded rods to the connectors
- Weights or varying size could then be added to the rods at varying distance to create a controlled amplifier
- If a group of failures are separated by a large margin the stress can be raised by an order of magnitude without breaking down the setup

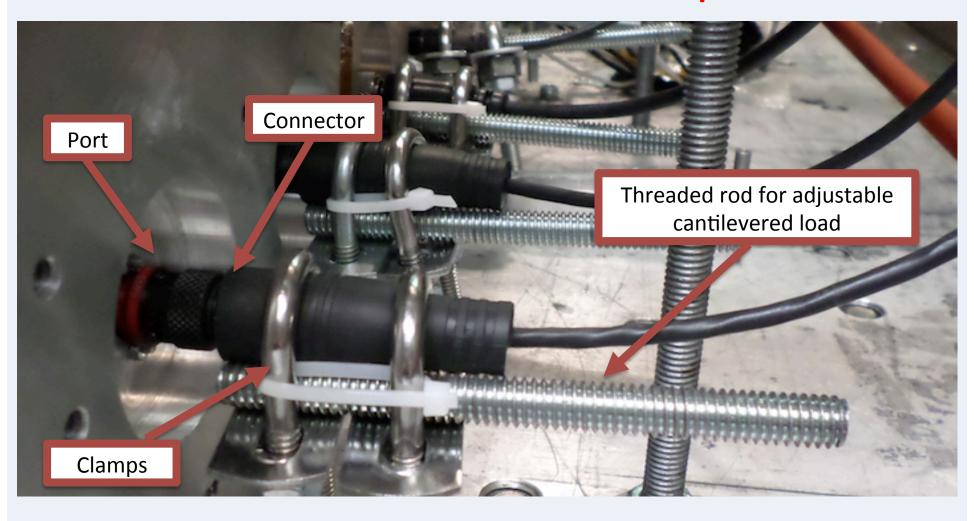








## **Cantilever Load Setup**



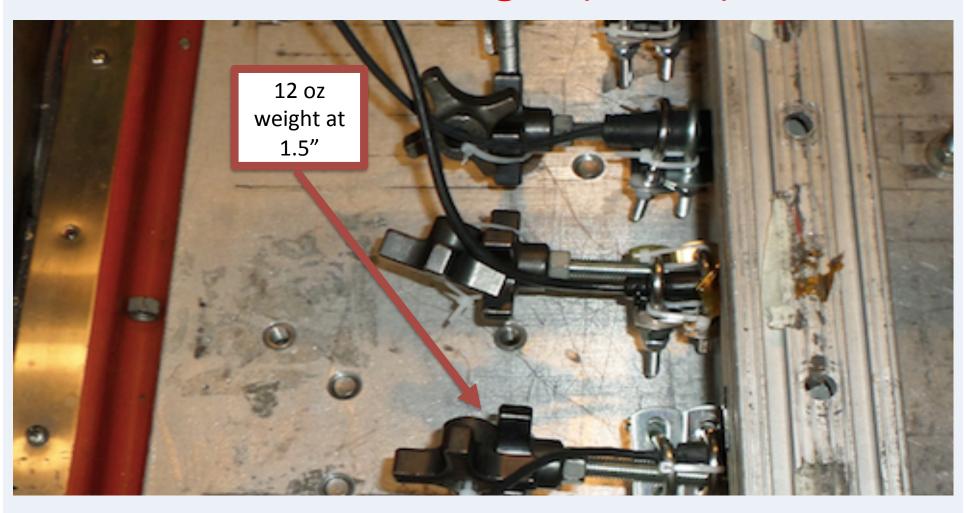








## 12 oz of weight (3/4 lb)



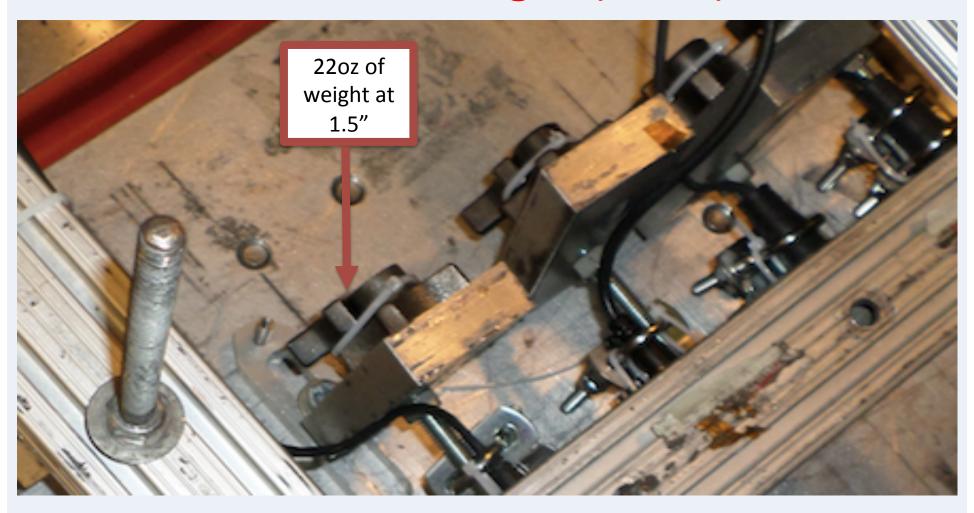








## 22 oz of weight (1.5lb)









#### Results

 The accelerated test development initiative resulted in the ability to apply enough cumulative stress to replicate the failures observed in the field on any connector configuration